# The Theoretical Minimum 

# Classical Mechanics - Solutions 

L02E03
Last version: tales.mbivert.com/on-the-theoretical-minimum-solutions/or github.com/mbivert/ttm

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May 10, 2023

Exercise 1. Use the chain rule to find the derivatives on each of the following functions:

$$
\begin{aligned}
g_{0}(t) & =\sin \left(t^{2}\right)-\cos \left(t^{2}\right) \\
\theta_{0}(\alpha) & =e^{3 \alpha}+3 \alpha \ln (3 \alpha) \\
x_{0}(t) & =\sin ^{2}\left(t^{2}\right)-\cos \left(t^{2}\right)
\end{aligned}
$$

Remark 1. We've slightly altered the functions names compared to what they have in the book. The reason will be apparent very soon.

Remark 2. As in previous exercises (e.g. L02E01), we'll be using some additional mathematical notation to avoid us the need to define functions. The meaning should be obvious from the context.

We will also use the prime notation to denote differentiation, as we also did in earlier exercises.
There are two main ways of proceeding: either applying the chain rule to each individual term of each function, for instance to compute $g^{\prime}$, we would fist compute $\left(\sin \left(t^{2}\right)\right)^{\prime}=\left(\sin \left(\left(u \mapsto u^{2}\right)(t)\right)\right)^{\prime}$, using the chain rule, then $\left(\cos \left(t^{2}\right)\right)^{\prime}$ in a similar fashion, etc.

Or, and we're going to use this approach as it's likely to have been expected one, we can consider each function "globally" as a composition of two smaller functions. While doing so, we will find that $g_{0}, \theta_{0}$ and $x_{0}$ are respectively created by composing functions $f, \theta$ and $x$ of an earlier exercise, with two simple functions $\left(v \mapsto v^{2}\right)$ and $(v \mapsto 3 v)$ :

$$
\begin{aligned}
& g_{0}(t)=(\underbrace{(u \mapsto \sin (u)-\cos (u))}_{g} \circ\left(v \mapsto v^{2}\right))(t) \\
& \theta_{0}(\alpha)=(\underbrace{\left(u \mapsto e^{u}+u \ln (u)\right)}_{\theta} \circ(v \mapsto 3 v))(t) \\
& x_{0}(t)=(\underbrace{\left(u \mapsto \sin ^{2}(u)-\cos (u)\right)}_{x} \circ\left(v \mapsto v^{2}\right))(t)
\end{aligned}
$$

Let's remember the derivative of $g, \theta$ and $x$, that we've computed in L02E01.

$$
\begin{aligned}
g^{\prime}(x) & =\cos (x)+\sin (x) \\
\theta^{\prime}(\alpha) & =e^{\alpha}+\ln (\alpha)+1 \\
x^{\prime}(t) & =(1+2 \cos t) \sin t
\end{aligned}
$$

Finally, let's recall the chain rule:

$$
\frac{d}{d t}(\psi \circ \varphi)=\frac{d}{d t}\left(\psi(\varphi(t))=\varphi^{\prime}(t) \psi^{\prime}(\varphi(t))\right.
$$

Then, the derivative of $\left(v \mapsto v^{2}\right)$ and $(v \mapsto 3 v)$ being respectively $(v \mapsto 2 v)$ and ( $v \mapsto 3$ ) (constant function), we have the following derivatives for our functions:

$$
\begin{aligned}
g_{0}^{\prime}(t) & =2 t\left(\cos t^{2}+\sin t^{2}\right) \\
\theta_{0}^{\prime}(\alpha) & =3\left(e^{3 \alpha}+\ln (3 \alpha)+1\right) \\
x_{0}^{\prime}(t) & =2 t\left(\left(1+2 \cos t^{2}\right) \sin t^{2}\right)
\end{aligned}
$$

