

# The Theoretical Minimum

## Classical Mechanics - Solutions

L10E01

Last version: [tales.mbivert.com/on-the-theoretical-minimum-solutions/](https://tales.mbivert.com/on-the-theoretical-minimum-solutions/) or [github.com/mbivert/ttm](https://github.com/mbivert/ttm)

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**Exercise 1.** *Prove Eq. (14)*

Eq. (14) of the book refers to:

$$\{F(q, p), p_i\} = \frac{\partial F(q, p)}{\partial q_i}$$

Where the brackets  $\{.,.\}$  are the Poisson Brackets: for  $A$  and  $B$  each two functions of  $2N$  variables  $\{p_i\}_{1 \leq i \leq N}$  and  $\{q_i\}_{1 \leq i \leq N}$ , ( $N \in \mathbb{N}$ ):

$$\{A, B\} = \sum_{i=1}^N \frac{\partial A}{\partial q_i} \frac{\partial B}{\partial p_i} - \frac{\partial A}{\partial p_i} \frac{\partial B}{\partial q_i}$$

And  $F(p, q)$  a function of  $q$  and  $p$ . There's a bit of ambiguity regarding what  $p$  and  $q$  are, which actually doesn't affect the derivation, but let's make things clear anyway. In the previous example, we proved that  $\{q^n, p\} = nq^{n-1}$ : in this case,  $N = 1$  and we had a single  $q$  and a single  $p$ .

But now we're asked to prove a result involving  $F(p, q)$  partially derived according to  $q_i$ , which implies, for the result not to be trivial, that  $F$  is a function of  $q_i$ , and thus that  $p$  and  $q$  are actually tuples of  $N$   $p_i$  and  $N$   $q_i$ .

So, let's expand the Poisson brackets to be evaluated, using the definition of the Poisson brackets:

$$\{F(q, p), p_i\} = \sum_{k=1}^N \frac{\partial}{\partial q_k} F(q_1, \dots, q_N, p_1, \dots, p_N) \frac{\partial p_i}{\partial p_k} - \frac{\partial}{\partial p_k} F(q_1, \dots, q_N, p_1, \dots, p_N) \frac{\partial p_i}{\partial q_k}$$

Now because  $p_i$  will never depends on  $q_k$ , as those are two distinct variables,  $\frac{\partial p_i}{\partial q_k} = 0$ , and the previous expression shrinks to:

$$\{F(q, p), p_i\} = \sum_{k=1}^N \frac{\partial}{\partial q_k} F(q_1, \dots, q_N, p_1, \dots, p_N) \frac{\partial p_i}{\partial p_k}$$

For similar reasons,  $\frac{\partial p_i}{\partial p_k} = \delta_i^k$ , and the previous expression shrinks again to:

$$\{F(q, p), p_i\} = \frac{\partial}{\partial q_i} F(q_1, \dots, q_N, p_1, \dots, p_N) = \boxed{\frac{\partial F(p, q)}{\partial q_i}}$$

**Remark 1.** *Eq. (15) of the book is to be proven as we did for Eq. (14).*

**Remark 2.** *Earlier in this section, the authors informally invited us to verify the properties of the Poisson brackets (anti-symmetry, linearity, product rule). I won't be doing it, because I think at this stage of the book, this should be elementary: you just have to replace the brackets by their definition, and re-arrange the terms, often using linearity of the differentiation/partial differentiation, and then switch back to expressions involving (the expected) Poisson brackets again.*